

Other type issues (arrays, structs...)

- we should examine the code needed to access array elements
- first, consider one-dimensional arrays, random access
- suppose our array indices start at base address B (usually 0 or 1, but could be any integer)
- given an array of N elements, each with size S
- the offset to element i is then $(i-B)*S$
- note that if B is 0 then this becomes simply $i*S$

1-D array, random access

- possible pseudo-asm to access $\text{Arr}[i]$, where $B=1$, $S=8$
 - `LoadAddr @Arr,R1 // copy Arr's addr to R1`
 - `Load i, R2 // copy i from mem to R2`
 - `subi 1,R2 // subtract B from i`
 - `multi 8,R2 // multiply by 8 to get offset to i`
 - `add R1,R2,R2 // compute full address of A[i]`
 - `Load R2,R3 // finally, R3 := Arr[i]`

Some optimizations

- possible pseudo-asm to access `Arr[i]`, where $B=1$, $S=8$
 - `LoadAddr @Arr,R1 // copy Arr's addr to R1`
 - `load i, R2 // copy i from mem to R2`
 - `// can get rid of subtract if B is 0`
 - `lshift 3,R2 // bit shift quicker than multiply`
 - `// often a combined load op availab, e.g.`
 - `loado R1,R2,R3 // R3 := Arr[i]`

1-dim, sequential access

- common to access a number of elements in order, e.g.
 - for $i = a$ to b : $Arr[i] = 0$;
- instead of computing from scratch each time:
 - compute addr for $Arr[a]$ normally
 - for each subsequent i , simply add the element size (e.g. 8)
- assumes elements are stored sequentially in memory

Multi-dim, sequential access

- for $r = m$ to n
 - for $c = a$ to b
 - $\text{Arr}[r][c] = 0$
- before first loop:
 - compute $\text{rowstart} = \text{addr of Arr}[r][a]$
 - $\text{offset} = 0$
- at end of each pass through inner loop
 - add element size to offset
- at end of each pass through outer loop
 - add Arr 's total row size to rowstart
 - set offset back to 0

Indirection vectors: 2-d

- each row of the array stored as one-dim array
- “outer” dimension of array is actually an array of pointers to the rows
 - `Arr[i]` points to i'th row
 - `Arr[i][j]` accesses j'th element of i'th row
- uses extra space (for the outer 1-d array), but rows no longer need to be contiguous

Access via indirection vector

- Arr actually holds address of indirection vector
- Suppose we want to iterate through all elements
 - `LoadAddr @Arr, R0 // get addr of indir vector`
 - repeat for each row
 - `LoadAddr R0,R1// get addr of row`
 - `loadi 0,R2 // offset to first element in row`
 - repeat for each element in row:
 - `loado R1,R2,R3 // R3 = Arr[0][0]`
 - `addi 8,R2`
 - `addi 8,R0 // R1 := addr holding start of next row`

Arrays as params

- usually passed as an address, even if goal is “by value”
- for multidim arrays, callee needs to know row sizes
- what if they're not known at compile time? e.g. dynamically allocated
- compiler can generate a descriptor: record of number of array dimensions and sizes
- compiler can pass a pointer to the descriptor as the array “parameter” (this ptr often called a dope vector)
- means adding extra code to callee to access descriptor

Character arrays as strings

- null terminated ($O(n)$ to find end) vs store size (extra storage needed)
- access generally the same as for arrays
- what if a “char” is smaller than the smallest addressable size in asm
 - need to add bitmask operations around char access!
- `concat(a,b)`:
 - either `a:=a.b` (simply copy b to end of a's space)
 - or return new string containing a.b
 - `length(a.b)`:
 - concatenate first then compute
 - or compute `length(a)+length(b)`

Structures/records

- as discussed earlier, need to map order/offsets of fields, padding or re-ordering for alignment rules
- `x.s` might be implemented like
 - `LoadAddr @X, R1`
 - `Loadi 12, R2 // supposing 12 is the offset to S`
 - `Loado R1,R2,R3 // R3 := x.s`

Arrays of structs

- could be implemented like programmer may expect, i.e. As an actual array of structs
- compiler could actually choose to implement it as a struct of arrays!
 - could provide more efficient sequential access when iterating across a fixed field
 - difference not visible to the programmer

Unions

- Allow programmer to specify a set of possible data types for the item
- Item given just enough memory to store largest of the data types in the set
 - `union num { int i; float f; } // num is int or float`
 - `num x;`
 - `x.i = 3; // store int 3 in x's memory space`
 - `x.f = 1.23; // overwrite x's space with float 1.23`
 - `int v = x.i; // use x's mem space as if type int,`
 - `// copying contents to v`

Pointers and ambiguity (again)

- cold memory address/reference
- complicate compiler's ability to keep things in registers
 - $*x$ could refer to same stored value as z , or as $*y$
 - could even refer to same stored value as $*(y + 600)$
- if compiler has each of the referenced values in registers then it can't know which ones are referring to the same “real” value
- has to take a safe/conservative approach and put things back in memory before/after uses